Auto-Bäcklund Transformation and Solitary-wave Solutions to Nonintegrable Generalized Fifth-order Nonlinear Evolution Equations

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We show that the application of the truncated Painlevé expansion and symbolic computation leads to a new class of analytical solitary-wave solutions to the general fifth-order nonlinear evolution equations which include Lax, Sawada-Kotera (SK), Kaup-Kupershmidt (KK), and Ito equations. Some explicit solitary-wave solutions are presented.

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While it is easy to write down in closed from a solitary wave solution for the simplest standard model, namely the Korteweg-de Vries (KdV) equation, it has proved quite difficult to obtain such solutions for the problems from which the KdV equation was derived as a First approximation [1]. As such KdV hierarchy models, we investigate the generalized nonintegrable fifth-order nonlinear evolution equations of the form [2]

$$u_t + \alpha u u_{xxx} + \beta u_x u_{xx} + \gamma u^2 u_x + u_{xxxxx} = 0$$
, (1)

where α , β , and γ are constant model parameters. This model includes the Lax [3], Kaup-Kupershmidt (KK) [4 - 7], Sawada-Kotela (SK) [9], and Ito equations [8]. As the constants α , β , and γ take different values, the properties of (1) drastically change. For instance, the Lax equation with $\alpha=10$, $\beta=20$, and $\gamma=30$, and the SK equation where $\alpha=\beta=\gamma=5$, are completely integrable. These two equations have N-soliton solutions and an infinite set of conservation laws. The KK equation, with $\alpha=10$, $\beta=25$, and $\gamma=20$, is also known to be integrable [6] and to have bilinear representations [10, 11], but the explicit form of its N-soliton solution is apparently not known. A

fourth equation in the model is the Ito equation, with $\alpha = 3, \beta = 6$, and $\gamma = 2$, which is not completely integrable but has a limited number of conservation laws [8]. More recently, using a simplified version of Hirota's method, Hereman and Nuseir [2] explicitly constructed multi-soliton solutions of the KK equation for which soliton solutions were not previously known. However, to our knowledge no attempt has been made for finding more general solitary-wave solutions other than the above mentioned models because of lengthy and nearly impossible calculations without proper symbolic computation packages. By utilizing the symbolic package Maple, Hong [12] recently found some analytical solitary-wave solutions to the general fifth-order water models in [13], with some constraints on the model parameters.

In this work, we make use of both the truncated Painlevé expansion and the symbolic computation method [14 - 17] to obtain an *auto-Bäcklund transformation* and certain explicit solitary-wave solutions for the generalized non-integrable fifth-order nonlinear evolution equation, which are different from the solutions of the models mentioned above [3 - 8].

A non-linear partial differential equation (NPDE) is said to possess the Painlevé property when the

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solutions of the NPDE are "single valued" about the movable, singularity manifold which is "noncharacteristic". To be more precise, if the singularity manifold is determined by

$$\phi(z_1, z_2, ..., z_n) = 0, \tag{2}$$

and $u = u(z_1, z_2, ..., z_n)$ is a solution of the NPD, then it is required that

$$u = \phi^{\alpha} \sum_{j=0}^{\infty} u_j \phi^j, \tag{3}$$

where $u_0 \neq 0$, $\phi = \phi(z_1, z_2, ..., z_n)$, $u_j = u_j(z_1, z_2, ..., z_n)$ are analytical function of (z_j) in the neighborhood of the manifold (3), and α is a negative, rational number. Substitution of (3) into the NPDE determines the allowed values of α and defines the recursion relation for u_j , j = 0, 1, 2, ... When the ansatz (3) is correct, the NPDE is said to possess the Painlevé property and is conjectured to be integrable [14, 17].

In order to find solitonic solutions for (1), we truncate the Painlevé expansion, (3), at the constant-level term in the senses of Tian and Gao [15] and Khater et al. [17],

$$u(x,t) = \phi^{-J}(x,t) \sum_{l=0}^{J} u_l(x,t) \phi^l(x,t).$$
 (4)

On balancing the highest-order contributions from the linear term (i. e. u_{xxxxx}) with the highest order contributions from the nonlinear term (i.e, u^2u_x), we get J=2, so that

$$u(x,t) = \frac{u_0(x,t)}{\phi^2(x,t)} + \frac{u_1(x,t)}{\phi(x,t)} + u_2(x,t).$$
 (5)

We will stay with the general assumption that $\phi_x \neq 0$ but will not initially impose any constraints on the model parameters α, β, γ . When substituting the above expressions into (1) with the symbolic program package Maple, we let the coefficients of like powers of ϕ vanish, so as to get the set of Painlevé-Bäcklund (PB) equations,

$$\phi^{-7}: -720 u_0 \phi_x^{5} - 12 \beta u_0^{2} \phi_x^{3} - 24 \alpha u_0^{2} \phi_x^{3} - 2 \gamma u_0^{3} \phi_x = 0, \tag{6}$$

$$\phi^{-6}: -30 \alpha u_1 u_0 \phi_x^{3} + 18 \alpha u_0^{2} \phi_x \phi_{xx} + 18 \alpha u_0 \phi_x^{2} u_{0,x} + 1200 u_0 \phi_x^{3} \phi_{xx} - 10 \beta u_0 \phi_x^{3} u_1 - 4 \beta u_0^{2} \phi_x \phi_{xx}$$

$$+ 14 \beta u_0 \phi_x^{2} u_{0,x} - 120 u_1 \phi_x^{5} - 5 \gamma u_0^{2} u_1 \phi_x + \gamma u_0^{2} u_{0,x} + 600 \phi_x^{4} u_{0,x} = 0, \tag{7}$$

$$\phi^{-5}: -6 \alpha u_0 \phi_x u_{0,xx} - 4 \gamma u_0^{2} \phi_x u_2 - 24 \alpha u_2 u_0 \phi_x^{3} + 6 \beta u_1 \phi_x^{2} u_{0,x} - 2 \beta u_1^{2} \phi_x^{3} + 4 \beta u_0 \phi_x u_1 \phi_{xx}$$

$$+ 18 \alpha u_1 \phi_x^{2} u_{0,x} + 24 \alpha u_1 u_0 \phi_x \phi_{xx} + 2 \gamma u_0 u_1 u_{0,x} - 4 \gamma u_0 u_1^{2} \phi_x + 6 \alpha u_0 \phi_x^{2} u_{1,x} + 10 \beta u_{1,x} u_0 \phi_x^{2}$$

$$- 2 \beta u_0 \phi_x u_{0,xx} - 6 \alpha u_0 \phi_{xx} u_{0,x} - 2 \beta u_{0,x} u_0 \phi_{xx} - 4 \beta \phi_x u_{0,x}^{2} - 720 \phi_x^{2} \phi_{xx} u_{0,x} + 120 \phi_x^{4} u_{1,x}$$

$$+ 240 u_1 \phi_x^{3} \phi_{xx} + \gamma u_0^{2} u_{1,x} - 240 u_0 \phi_x^{2} \phi_{xxx} - 360 u_0 \phi_x \phi_{xx}^{2} - 2 \alpha u_0^{2} \phi_{xxx} - 6 \alpha u_1^{2} \phi_x^{3}$$

$$- 240 \phi_x^{3} u_{0,xx} = 0, \tag{8}$$

$$\phi^{-4}: \gamma u_1^{2} u_{0,x} - \gamma u_1^{3} \phi_x + 90 \phi_{xx}^{2} u_{0,x} + 60 \phi_x^{2} u_{0,xxx} + \beta u_{0,x} u_{0,xx} - 6 \alpha u_2 u_1 \phi_x^{3} + 18 \alpha u_2 u_0 \phi_x \phi_{xx}$$

$$+ 2 \gamma u_0 u_2 u_{0,x} - 3 \alpha u_0 u_1 \phi_{xxx} + 2 \gamma u_0 u_1 u_{1,x} + 6 \alpha u_1 \phi_x^{2} u_{1,x} + 4 \beta u_1 \phi_x^{2} u_{1,x} + 18 \alpha u_2 \phi_x^{2} u_{0,x}$$

$$+ 6 \alpha u_1 \phi_x u_{0,xx} - \beta u_1 \phi_x u_{0,xx} - \beta u_0 \phi_x u_1 \phi_{xx} - 6 \alpha u_1 \phi_{xx} u_{0,x} + 6 \alpha u_1^{2} \phi_x \phi_{xx} + \beta u_1^{2} \phi_x \phi_{xx}$$

$$- 6 \gamma u_1 u_2 u_0 \phi_x - 2 \beta u_0 \phi_x u_{1,xx} + 6 \beta u_{2,x} u_0 \phi_x^{2} - 2 \beta u_{1,x} u_0 \phi_{xx} - 3 \alpha u_0 u_{1,xx} \phi_x$$

$$+ 180 \phi_x \phi_{xx} u_{0,xx} - 6 \beta u_{0,x} u_{1,xx} + 6 \beta u_{2,x} u_0 \phi_x^{2} - 2 \beta u_{1,x} u_0 \phi_{xx} - 3 \alpha u_0 u_{1,xx} \phi_x$$

$$+ 180 \phi_x \phi_{xx} u_{0,xx} - 6 \beta u_{0,x} u_{1,xx} + 6 \beta u_{2,x} u_0 \phi_x^{2} - 2 \beta u_{1,x} u_0 \phi_{xx} - 3 \alpha u_0 u_{1,x} \phi_{xx} - 6 \alpha u_0 u_0 \phi_x \phi_{xx}$$

$$+ \alpha u_0 u_{0,xxx} - 180 \phi_x^{2} u_{1,x} \phi_{xx} - 60 u_1 \phi_x^{2} \phi_{xxx} - 90 u_1 \phi_x \phi_{xx}^{2} + 30 u_0 \phi_x \phi_{xxx} = 0, \tag{9}$$

$$\phi^{-3}: \alpha u_0 u_{1,xxx} + \gamma u_{1,x} u_1^2 - 2\beta u_{2,x} u_0 \phi_{xx} - 2\beta u_0 \phi_{x} u_{2,xx} + 2\gamma u_0 u_1 u_{2,x} - 2 u_0 \phi_{t} - 2 u_0 \phi_{xxxx}$$

$$- 4\beta u_{2,x} \phi_{x} u_{0,x} + 20 u_{1,xxx} \phi_{x}^2 + 30 \phi_{xx}^2 u_{1,x} - 20 \phi_{xx} u_{0,xxx} - 10 \phi_{x} u_{0,xxxx} - 10 \phi_{xxxx} u_{0,x}$$

$$- 20 \phi_{xxx} u_{0,xx} + 6\alpha u_2 u_1 \phi_{x} \phi_{xx} + 2\gamma u_1 u_2 u_{0,x} + 2\beta u_{2,x} u_1 \phi_{x}^2 - 3\alpha u_1 u_{1,xx} \phi_{x} - 3\alpha u_1 u_{1,x} \phi_{xx}$$

$$- \beta u_{1,x} u_1 \phi_{xx} - \beta u_{1,xx} u_1 \phi_{x} + 2\gamma u_{1,x} u_0 u_2 - 2\alpha u_2 u_0 \phi_{xxx} - 2\gamma u_2^2 u_0 \phi_{x} + 6\alpha u_2 \phi_{x}^2 u_{1,x}$$

$$- 6\alpha u_2 \phi_{x} u_{0,xx} - 6\alpha u_2 \phi_{xx} u_{0,x} - 2\gamma u_1^2 u_2 \phi_{x} + 40 \phi_{x} u_{1,x} \phi_{xxx} + \alpha u_1 u_{0,xxx} - 2\beta u_{1,x}^2 \phi_{x}$$

$$+ \beta u_{1,xx} u_{0,x} + \beta u_{1,x} u_{0,xx} + 60 \phi_{x} u_{1,xx} \phi_{xx} + 10 u_1 \phi_{x} \phi_{xxxx} + 20 u_1 \phi_{xx} \phi_{xxx} - \alpha u_1^2 \phi_{xxx}$$

$$+ 10 \alpha \phi_{x}^2 u_{1,xxx} - 3\mu \phi_{x} u_{0,xx} - 5\alpha \phi_{x} u_{0,xxx} - 4\gamma u_{1,x}^2 \phi_{x} + 3\mu \phi_{x}^2 u_{1,x} = 0,$$

$$\phi^{-2}: -u_1 \phi_{t} + \alpha u_2 u_{0,xxx} - u_1 \phi_{xxxxx} - 2\beta u_{2,x} u_{1,x} \phi_{x} + 2\gamma u_1 u_2 u_{1,x} - \gamma u_2^2 u_1 \phi_{x} - \alpha u_2 u_1 \phi_{xxx}$$

$$+ 2\gamma u_{2,x} u_0 u_2 - 3\alpha u_2 u_{1,x} \phi_{xx} - 3\alpha u_2 u_{1,xx} \phi_{x} - \beta u_{2,xx} u_1 \phi_{x} - \beta u_{2,xx} u_1 \phi_{xx} + u_{0,xxxx} + u_{0,t}$$

$$+ \beta u_{1,x} u_{1,xx} - 10 u_{1,xx} \phi_{xxx} - 5u_{1,x} \phi_{xxxx} + \gamma u_2^2 u_{0,x} + \gamma u_{2,x} u_1^2 + \alpha u_1 u_{1,xxx} - 5u_{1,xxxx} \phi_{x}$$

$$+ \alpha u_0 u_{2,xxx} - 10 u_{1,xxx} \phi_{xx} + \beta u_{2,x} u_{0,xx} + \beta u_{2,xx} u_{0,x} = 0,$$

$$(11)$$

$$\phi^{-1}: \alpha u_1 u_{2,xxx} + \alpha u_2 u_{1,xxx} + u_{1,xxxx} + 2\gamma u_1 u_2 u_{2,x} + \gamma u_2^2 u_{1,x} + \beta u_{1,x} u_{2,xx} + \beta u_{2,x} u_{1,xx} + u_{1,t} = 0,$$

$$(12)$$

$$\phi^{0}: u_2 \text{ needs to satisfy the original equation, i.e., }$$

 $u_{2,xxxx} + \beta u_{2,x}u_{2,xx} + \alpha u_2u_{2,xxx} + u_{2,t} + \gamma u_2^2 u_{2,x} = 0$ (13)The set of (5) and (6 - 13) constitutes an auto-Bäcklund transformation, if the set is solvable with respect

to $\phi(x,t)$, $u_0(x,t)$, $u_1(x,t)$ and $u_2(x,t)$ [15, 16]. Equation (6) brings out three possibilities for $u_0(x,t)$:

$$u_0^{\rm I} = 0, \quad u_0^{\rm II} = 3 \frac{(-\beta - 2\alpha + \mathcal{H})\phi_x^2}{\gamma}, \quad u_0^{\rm III} = 3 \frac{(-\beta - 2\alpha - \mathcal{H})\phi_x^2}{\gamma},$$
 (14)

where $\mathcal{H} \equiv \sqrt{\beta^2 + 4\beta\alpha + 4\alpha^2 - 40\gamma}$. Some complicated symbolic manipulations are required to find general solutions for the remaining $u_1(x,t)$ and $u_2(x,t)$. However, due to increasing complexities in the symbolic computations, a long CPU time is required. Thus, in the following, in order to shorten the computation time, we constrain the model parameters by requiring

$$\mathcal{H} = 0 \Longrightarrow \alpha = -\beta/2 + \sqrt{10\gamma} \text{ or } \alpha = -\beta/2 - \sqrt{10\gamma}.$$
 (15)

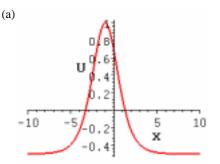
In the rest of the paper, we consider a solution family for the case of the non-trivial solution $u_0^{\rm II}$ with the first constraint $\alpha = -\beta/2 + \sqrt{10\gamma}$. Of course, other classes of solitary-wave solutions can be found from u^{III} and the second constraint on α, β, γ .

After substituting u_0^{II} and α into (7), we obtain

$$u_1(x,t) = \frac{12\phi_{xx}(5\beta + 2\sqrt{10\gamma})}{\beta\sqrt{10\gamma} + 4\gamma}.$$
 (16)

Subsequently, we get the following solution for $u_2(x, t)$ from (9):

$$u_2(x,t) = \frac{-32 \gamma \phi_x \phi_{xxx} + 15 \beta^2 \phi_{xx}^2 - 20 \beta^2 \phi_x \phi_{xxx} - 4 \phi_x \phi_{xxx} \sqrt{10\gamma} \beta + 24 \phi_{xx}^2 \gamma}{\phi_x^2 (\sqrt{10\gamma} \beta^2 + 8 \gamma \beta + 16 \gamma^{3/2})}.$$
 (17)



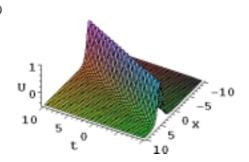


Fig. 1. (a) Typical sech²-shpaed solitary-wave solution u(x,0) in (21) with parameters $A=1, B=1, C_1=1, \beta=-2, \gamma=10$, and $\alpha=-\beta/2+\sqrt{10\gamma}=11$. (b) u(x,t) shows the solitary wave property that the amplitude becomes finite as |x| approaches infinity.

Thus, we are able to find a class of analytical solutions u(x,t) in terms of $u_0^{\rm II}$, u_1 , u_2 in (14 - 17) with an arbitrary function $\phi(x,t)$ constrained by the remaining equations (10 - 13). We note that, once a Bäcklund transformation is discovered and a set of "seed" solutions is given, one will be able to find an infinite number of solutions by repeated applications of the transformation, i. e., to generate a hierarchy of solutions with increasing complexity. In the rest of the paper we will find a family of some exact analytical solutions of (1).

Sample Solution

A trial solution

$$\phi(x, t) = 1 + e^{Q(x, t)}$$
, where $Q(x, t) = A(t)x + B(t)$ (18)

is substituted into the remaining constraint equations (10 - 13). From (10), we find

$$\phi^{-3} \& x : A(t)' = 0 \implies A(t) = A = \text{constant.}$$
 (19)

Then, we obtain B(t)' from the terms of ϕ^{-3} and integrate it over t to get

$$B(t) = \frac{-\mathcal{R} \cdot t - \mathcal{S}}{4\mathcal{T}},$$

$$\begin{split} \mathcal{R} &\equiv 10500 \, A^5 \sqrt{10} \beta^6 \gamma - 62720 \, A^5 \sqrt{10} \gamma^3 \beta^2 \\ &+ 13750 \, A^5 \beta^7 \sqrt{\gamma} - 97280 \, A^5 \gamma^{7/2} \beta \\ &- 201600 \, A^5 \beta^3 \gamma^{5/2} + 14000 \, A^5 \beta^5 \gamma^{3/2} \\ &- 28000 \, A^5 \sqrt{10} \beta^4 \gamma^2 - 6144 \, A^5 \sqrt{10} \gamma^4 \\ &+ 625 \, A^5 \beta^8 \sqrt{10}, \end{split}$$

$$\begin{split} \mathcal{S} &\equiv -224000 \, C_1 \beta^3 \gamma^{5/2} - 2500 \, C_1 \beta^7 \sqrt{\gamma} \\ &- 84000 \, C_1 \beta^5 \gamma^{3/2} - 71680 \, C_1 \gamma^{7/2} \beta \\ &- 53760 \, C_1 \sqrt{10} \gamma^3 \beta^2 - 4096 \, C_1 \sqrt{10} \gamma^4 \\ &- 7000 \, C_1 \sqrt{10} \beta^6 \gamma - 56000 \, C_1 \sqrt{10} \beta^4 \gamma^2, \end{split}$$

$$\mathcal{T} &\equiv 1024 \gamma^4 \sqrt{10} + 1750 \, \sqrt{10} \beta^6 \gamma + 14000 \, \sqrt{10} \beta^4 \gamma^2 \end{split}$$

+
$$13440\sqrt{10}\gamma^3\beta^2 + 56000\beta^3\gamma^{5/2} + 625\beta^7\sqrt{\gamma}$$

+ $21000\beta^5\gamma^{3/2} + 17920\gamma^{7/2}\beta$, (20)

where C_1 is the constant of integration. Combining all terms, we find a family of analytical solutions of (1) as

$$u(x,t) = 3 \frac{(-\beta - 2\alpha + \mathcal{H})\phi_{x}^{2}}{\gamma} \cdot \frac{1}{(1 + e^{Q(x,t)})^{2}} + \frac{12\phi_{xx}(5\beta + 2\sqrt{10\gamma})}{\beta\sqrt{10\gamma} + 4\gamma} \cdot \frac{1}{1 + e^{Q(x,t)}} - \left[32\gamma\phi_{x}\phi_{xxx} - 15\beta^{2}\phi_{xx}^{2} + 20\beta^{2}\phi_{x}\phi_{xxx} + 4\phi_{x}\phi_{xxx}\sqrt{10\gamma}\beta - 24\phi_{xx}^{2}\gamma\right] - \left[\phi_{x}^{2}(\sqrt{10\gamma}\beta^{2} + 8\gamma\beta + 16\gamma^{3/2})\right]$$
(21)

with the trial function $\phi(x, t)$ in (18) with Q(x, t) in (19, 20).

In the following we show that our solutions indeed have solitary-wave properties by presenting some figures from the family: We choose, as an example, a set of arbitrary constants; A = 1, B = 1, and $C_1 = 1$

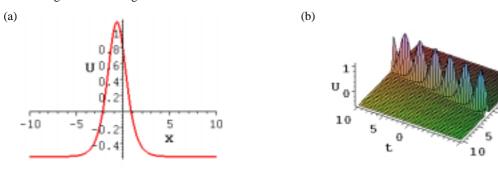


Fig. 2. (a) Sech²-shaped solitary-wave solution u(x,0) with parameters $A=1, B=1, C_1=1, \beta=2, \gamma=40$, and $\alpha=19$. (b) u(x,t) shows the breather solitary-wave solution behavior.

with the constraint $\alpha = -\beta/2 + \sqrt{10\gamma}$. Figures 1 and 2 correspond to $(\beta = -2, \gamma = 10, \alpha = 11)$ and $(\beta = 2, \gamma = 40, \alpha = 19)$, respectively. Firstly, we note that u(x,0) in Figs. 1(a) and 2(a) are both $\mathrm{sech}(x)^2$ -shaped solutions. From Figs. 1(b) and 2(b) we understand that in both cases the solutions have solitary wave property, i. e., u(x,t) tends to a finite value as |x| approaches infinity. Interestingly, Fig. 2(b) shows a breather solitary-wave solution.

To sum up, with symbolic computations and the truncated Painlevé expansion analysis, we showed that Bäcklund ransformations exist for the generalized fifth-order non-integrable nonlinear evolution

equation. We found a class of analytical solutions u(x,t) to (1) in terms of $u_0^{\rm II}$, u_1 , u_2 in (14 - 17) with an arbitrary function $\phi(x,t)$ constrained by (10 - 13). A sample solution family for u(x,t) was found in Eq.(21) with the constraint $\alpha = -\beta/2 + \sqrt{10\gamma}$. More solitary-wave families can be found from $u^{\rm III}(x,t)$ and other constraints on α , β , γ in (15).

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